



AnaGate CAN F2

Ethernet / CAN FD Gateway

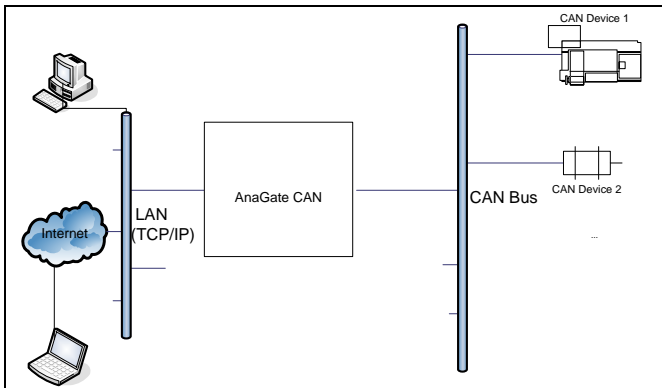
Product overview

The AnaGate CAN F2 gateway connects a PC, an embedded PC or other general device to up to 2 CAN buses via the TCP/IP network protocol (Ethernet). The AnaGate CAN F2 works as a device with no own CAN identifier on the bus.

The CAN messages are transparently embedded in TCP/IP telegrams to enable communication with any CAN device on the CAN network. This means that a CAN network can be addressed over the Internet or from multiple different PC's over a network. Higher protocol layers e.g. CANopen, Devicenet or J1939 can be used by the host system too.

Gateway mode

In the gateway mode the CAN messages are transferred transparently over TCP/IP between the CAN network and the host platform (e.g. PC) in both directions.



Listen mode

In the listen mode messages can be recorded without influencing the CAN bus.

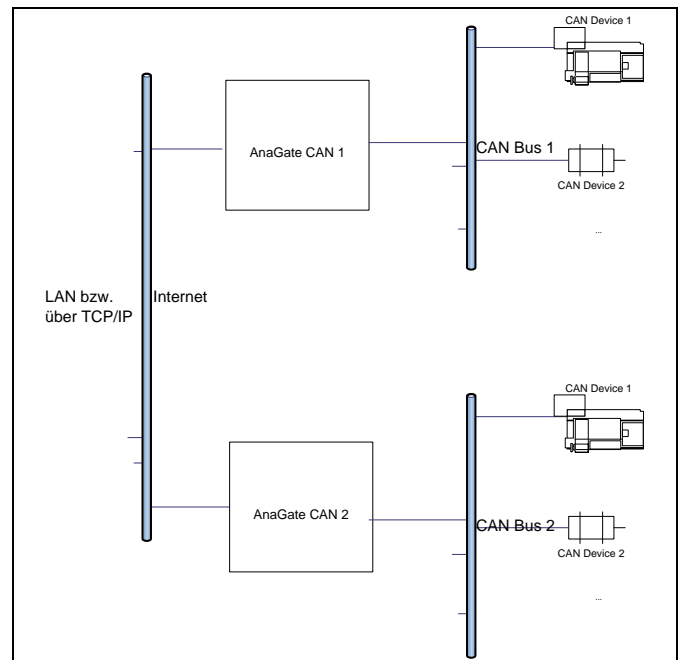
Bridge mode

In the bridge mode two arbitrary CAN networks are bridged together internally.

LAN Bridge mode

In the LAN bridge mode each CAN interface can be interconnected to an arbitrary CAN network by an

additional AnaGate CAN model.



Software interface

The application protocol is based on the TCP/IP protocol and is described in detail in the documentation.

Thus the access to the AnaGate CAN F2 device can be programmed via native calls to the TCP/IP socket interface. This means that any communication partner with a LAN (TCP/IP) interface is able to communicate with the AnaGate CAN F2.

Accessing the device with the supplied windows application library (DLL) is much more comfortable and can be used with a conventional programming language.

Technical specifications

Measurements	L x W x H	155 mm x 105 mm x 40 mm
	Weight	approx. 270 g
Power supply	Input voltage	9 .. 28 V DC or optional over PoE+ (802.3at Type 2)
	Power consumption	about 5W (without USB or I/O devices)
Temperature	Operating/Storage	-20 .. +70°C / -40 .. +85°C
System	Processor	Dual ARM Cortex A9 (1GHz), 512MB RAM, 4GB eMMC Flash
	Operating system	Linux kernel 4.15
CAN Bus 2.0B und FD	Nominal Baudrate	20 kbps .. 1 Mbps
	Data Bit Rate	500 kbps .. 8 Mbps
	Conformity	ISO 11898-1:2015 und non-ISO CAN FD (Bosch)
	CAN Controller	2x MCP2518FD
	CAN Interface	2x ISO 11898-2, galvanisch entkoppelt (1,5 kVrms)
	Interface	2x 4-polige Anschlussklemme mit CAN_H, CAN_L (Pitch 3.81) oder 4x M12 Anschlussklemme mit CAN_H, CAN_L
Modes of operation	Gateway mode	Multiple host controllers can receive/transmit CAN messages.
	Listen mode	Recording of CAN message without CAN bus influences..
	Bridge mode	2 CAN networks are connected internally.
	LAN Bridge mode	Both CAN interfaces can be interconnected to an arbitrary CAN network via LAN or internet.
LAN interface	Baudrate	10/100/1000 Mbps
	TCP/IP	Static or dynamic IP address (DHCP), configurable via web interface.
	Interface	RJ45 plug
USB 2.0	Interface	1x USB Host, 1x OTG Type A connector
Analogue IO:	Inputs	4 (0-24V , $R_i \sim 500k\Omega$)
	Outputs	4 (0,5V-min(24,5V, V_{Input})), $I_{max}=250mA$, short-circuit-safe
EC directives:		CE, RoHS.
Software:	Configuration	Via HTTP interface.
	CAN Monitor	Windows program to access CAN bus via AnaGate CAN.
Programming:	Native	Via socket interface using a documented application protocol.
	Windows (PC)	Via application library (32/64-bit DLL) using a standard programming language (e.g. C/C++, Delphi).
	Linux (PC)	Via static library ($g++$ V4.6, 32/64bit) or socketCAN.
	CANopen	OpenSource driver for CANFestival.
	Embedded Linux	Support (e.g. ARM9, Raspberry Pi) is available upon request.

Ordering information

Order number	Scope of delivery
GT-CAN-F2	AnaGate CAN F2 including CD-ROM with documentation, software API as a DLL for Windows 7/8/10 (32/64bit)
GT-SCOUT	CANscout - Professional Windows® software communicating with CAN- and CAN-FD networks via AnaGate CAN hardware series (CD,Windows)